

iBoat BSA

Vehicle Specifications

Hull dimension (L × W × H)	1035mm*560mm*345mm
Material	Carbon fiber, Rubber Bumper
Anti-wave & Wind	3rd wind level & 2nd wave level
Waterproof	IP67
Indicator light	Two-color light
Camera	360° omnidirectional video
Anticollision sensor	Detection distance 5-30 meters
Propeller type	Brushless DC
Direction control	Veering without steering engine
Maximum speed	6m/s
Battery endurance	10 hours@1.5m/s(two batteries)

Controller

System	Android 7.0, storage 5GB; SD Card supported
Software	SLHydro USV, an Android software for bathymetric surveys
Display	7 inches
Waterproof	IP67
R/C communication	2.4 GHz
Transmission range	Bridge Mode: 1.3 km (RF point-to-point in real-time) 4G Mode: Unlimited Distance (4G network transmission)
Navigation mode	Manual or Auto-Pilot

GNSS Performance

Satellite system	BDS B1/B2/B3, GPS L1/L2/L5, GLONASS L1/L2, Galileo E1/E5
Channel	432
Single point position(RMS)	±0.5m + 1 ppm
DGNSS positioning accuracy	±0.25m + 1 ppm
RTK Positioning accuracy	H: ±8mm + 1 ppm RMS V: ±15mm + 1 ppm RMS
Heading accuracy	0.2° @1 m baseline
Data formats	RTCM V3.0/3.2 input NMEA 0183 output NTRIP, TCP/IP

Single Beam Echo Sounder

Depth range	0.15m - 200m
Accuracy	±0.01m + 0.1% × D (D is the depth of water)
Frequency	200 kHz
Beam angle	5±0.5°

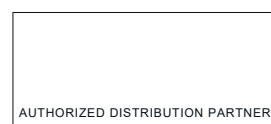
Software

Hi-Survey Boat	Project management: support project creation, application etc. Coordinate system: built-in coordinate system worldwide, support coordinate transformation and grid Mission planning: planning waypoints/lines, setting boat speed etc. Auto-pilot: auto course and auto return Echogram: automatic tracking depth, echo real-time display Data acquisition: real-time acquisition of positioning and bathymetry data
HiMAX	Data post-processing software. Support import Hi-Survey Boat project, analog signal superimposed digital bathymetry, feature point sampling, data correction, and output various of data formats



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iBoat BSA

An Android-powered USV system
for bathymetric surveys



iBoat BSA

USVs (Unmanned Surface Vehicles) are widely used in hydrographic surveys, environmental monitoring, and water search and rescue. Among them, hydrographic surveying is the most used and developed field. When a hydrological survey is facing many unknown waters, it usually takes a long time navigation and requires high accuracy, which poses great challenges to the safety and health of surveyors.

The hydrographic survey USV combines various complex systems to offer users the simple and efficient operation mode. With double hull design, iBoat BSA USV integrates the GNSS system, bathymetry system, communication system and autonomous navigation system, which ensures both efficient surveying and safe navigation.

Top 3 Challenges about USV

1



Usability

It is complicated and a waste of time repeating the unnecessary operational processes in many instances.

2



Functionality

It is applicable to various environments with abundant functions which makes the surveying more convenient.

3

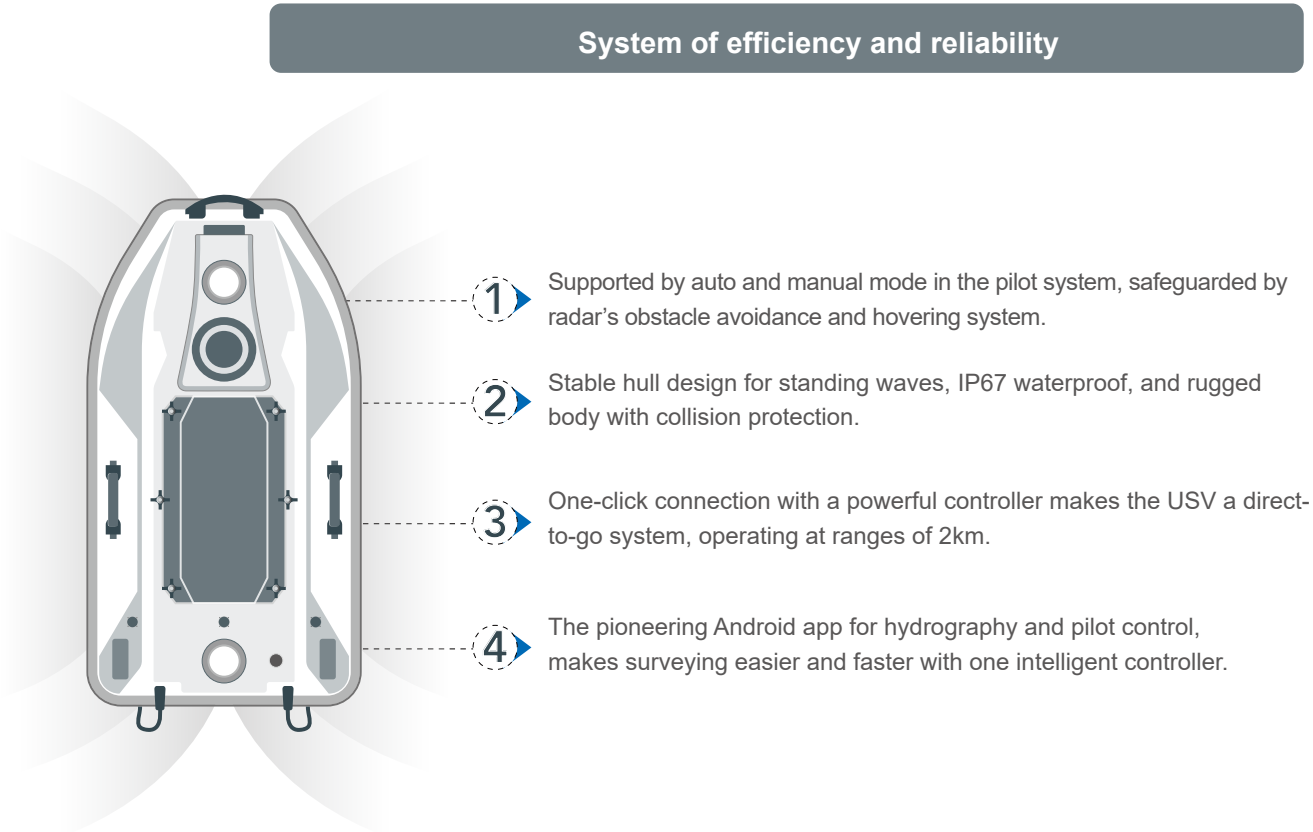


Reliability

It is important to avoid USV from sinking and wrecking. Besides, every part should be maintained in good quality for such a complex system.



iBoat BSA bathymetric USV system



Usability

- Operate in One Versatile app
- Time-saving Turn on and Survey
- Network without Base Station
- Integration with GNSS and SBES
- Connection with Indicator Lights



Functionality

- Stable Hovering Function
- Avoid Collision with Obstacles
- Real-time Video Patrol
- 4G Remote Control
- Auto-reverse in the Shallows



Reliability

- IP67 Double Hull
- Anti-Collision & Wear-Resisting
- IHO Standard & CE Certification
- Automotive Grade INS Integration
- Onboard Water Depth Logging